

# Sufficiency and minimal sufficiency

# Where we are and where we're going

So far:

- we know how to calculate MLEs
  - we know that in terms of MSE, MLEs are asymptotically the "best" we can do (under regularity conditions)
    - asymptotically unbiased
    - asymptotic variance is CRLB
  - we also know how to Rao-Blackwellize an unbiased estimator to improve MSE
    - condition on sufficient statistics
  - sufficient statistics contain all the info we need to calculate MLEs
- Currently:
- how do we find sufficient statistics?

Up next:

- Are there more "compact" sufficient statistics?
- when do sufficient statistics give us a best unbiased estimator?

## Recap: factorization theorem

Let  $x_1, \dots, x_n$  be a sample with joint probability function  $f(x_1, \dots, x_n | \theta)$ . A statistic  $T \equiv T(x_1, \dots, x_n)$  is sufficient for  $\theta$  if and only if there exist function  $g(t|\theta)$  and  $h(x_1, \dots, x_n)$  such that, for all possible  $x_1, \dots, x_n$  and all possible  $\theta$ ,

$$f(x_1, \dots, x_n | \theta) = \underbrace{g(T(x_1, \dots, x_n) | \theta)}_{\text{joint distribution only depends on } \theta \text{ through the sufficient statistic}} h(x_1, \dots, x_n)$$

Pf: (we will prove for discrete distributions)

① Suppose the functions  $g$  &  $h$  exist. WTS  $T$  is sufficient.

$$\begin{aligned} f(x_1, \dots, x_n | T, \theta) &= \frac{f(x_1, \dots, x_n, T(x_1, \dots, x_n) | \theta)}{f(T(x_1, \dots, x_n) | \theta)} \\ &= \frac{f(x_1, \dots, x_n | \theta)}{f(T(x_1, \dots, x_n) | \theta)} = \frac{g(T(x_1, \dots, x_n) | \theta) h(x_1, \dots, x_n)}{\sum_{\substack{y_1, \dots, y_n \\ T(y_1, \dots, y_n) = T(x_1, \dots, x_n)}} f(y_1, \dots, y_n | \theta)} \end{aligned}$$

$$\frac{g(T(x_1, \dots, x_n) | \theta) h(x_1, \dots, x_n)}{\sum_{\substack{y_1, \dots, y_n \\ T(y_1, \dots, y_n) = T(x_1, \dots, x_n)}} f(y_1, \dots, y_n | \theta)}$$

$$= \frac{g(\cancel{T(x_1, \dots, x_n)} | \theta) h(x_1, \dots, x_n)}{g(\cancel{T(x_1, \dots, x_n)} | \theta) \sum_{\substack{y_1, \dots, y_n \\ T(y_1, \dots, y_n) = T(x_1, \dots, x_n)}} h(y_1, \dots, y_n)}$$

$$\frac{g(T(x_1, \dots, x_n) | \theta) h(x_1, \dots, x_n)}{\sum_{\substack{y_1, \dots, y_n \\ T(y_1, \dots, y_n) = T(x_1, \dots, x_n)}} g(T(y_1, \dots, y_n) | \theta) h(y_1, \dots, y_n)}$$

$$= \frac{h(x_1, \dots, x_n)}{\sum_{\substack{y_1, \dots, y_n \\ T(y_1, \dots, y_n) = T(x_1, \dots, x_n)}} h(y_1, \dots, y_n)} \quad (\text{does not depend on } \theta)$$

✓

② Suppose  $T$  is a sufficient statistic.

Let  $g(t | \theta) = P_\theta(T(X_1, \dots, X_n) = t)$

$h(x_1, \dots, x_n) = P(X_1, \dots, X_n = x_1, \dots, x_n | T(X_1, \dots, X_n) = T(x_1, \dots, x_n))$  (does not depend on  $\theta$ )

$$\begin{aligned} f(x_1, \dots, x_n | \theta) &= P_\theta(X_1, \dots, X_n = x_1, \dots, x_n) \\ &= P_\theta(X_1, \dots, X_n = x_1, \dots, x_n \text{ and } T(X_1, \dots, X_n) = T(x_1, \dots, x_n)) \\ &= P_\theta(T(X_1, \dots, X_n) = T(x_1, \dots, x_n)) P(X_1, \dots, X_n = x_1, \dots, x_n | T(X_1, \dots, X_n) = T(x_1, \dots, x_n)) \\ &= g(T(x_1, \dots, x_n) | \theta) h(x_1, \dots, x_n) \end{aligned}$$

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## Example

Suppose  $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$  with  $\mu$  and  $\sigma^2$  unknown. Let  $\theta = (\mu, \sigma^2)$ .

Use the factorization theorem to find a sufficient statistic for  $\theta$ .  
(The dimension of the statistic will be greater than 1).

$$T = (\bar{X}, S)$$

$$T = (\bar{X}, S^2)$$

$$T = \left( \sum_i X_i, \sum_i X_i^2 \right)$$

$$X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$$

$$\begin{aligned}
 f(x_1, \dots, x_n | \mu, \sigma^2) &= \left( \frac{1}{\sqrt{2\pi\sigma^2}} \right)^n \exp \left\{ -\frac{1}{2\sigma^2} \sum_i (x_i - \mu)^2 \right\} \\
 &= \left( \frac{1}{\sqrt{2\pi\sigma^2}} \right)^n \exp \left\{ -\frac{1}{2\sigma^2} \left( \sum_i x_i^2 - 2\mu \sum_i x_i + n\mu^2 \right) \right\} \\
 &= g \left( \sum_i x_i, \sum_i x_i^2 | \mu, \sigma^2 \right) \\
 &= g \left( \sum_i x_i, \sum_i x_i^2 | \mu, \sigma^2 \right) \underbrace{h(x_1, \dots, x_n)}_{=1}
 \end{aligned}$$

$$\text{Sufficient statistic} = \left( \sum_i x_i, \sum_i x_i^2 \right)$$

$$\text{also do: } \left( \frac{1}{n} \sum_i x_i, \frac{1}{n-1} \sum_i (x_i - \bar{x})^2 \right)$$

$$\sum_i (x_i - \bar{x})^2 = \sum_i x_i^2 - n(\bar{x})^2$$

Is the dimension of a sufficient statistic always = dimension of  $\Theta$ ?

NO: (a)  $(X_1, X_2, X_3, \dots, X_n)$  is sufficient

(b) Ex:  $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Uniform}[\theta, \theta+1]$

minimal sufficient statistic:  $(X_{(1)}, X_{(n)})$

# Sufficient statistics as partitions

Suppose  $X_1, X_2, X_3 \stackrel{i.i.d}{\sim} \text{Bernoulli}(p)$ , we know  $T = X_1 + X_2 + X_3$  is sufficient

| $(x_1, x_2, x_3)$ | $T(x_1, x_2, x_3)$ | $P(x_1, x_2, x_3   T)$ |                       |
|-------------------|--------------------|------------------------|-----------------------|
| $(0, 0, 0)$       | 0                  | 1                      | $\mathbb{R}$          |
| $(1, 0, 0)$       | 1                  | $1/3$                  | ← equivalence classes |
| $(0, 1, 0)$       | 1                  | $1/3$                  |                       |
| $(0, 0, 1)$       | 1                  | $1/3$                  |                       |
| $(1, 1, 0)$       | 2                  | $1/3$                  | ←                     |
| $(1, 0, 1)$       | 2                  | $1/3$                  |                       |
| $(0, 1, 1)$       | 2                  | $1/3$                  |                       |
| $(1, 1, 1)$       | 3                  | 1                      | ↓                     |

$T(x_1, x_2, x_3)$  partitions space  $(x_1, x_2, x_3)$  into sets  $B_1, B_2, B_3, B_4$   
 $B_1 = \{(x_1, x_2, x_3) : T=0\}$ ,  $B_2 = \{(x_1, x_2, x_3) : T=1\}$ , etc.  
 $T$  is sufficient  $\Leftrightarrow f((x_1, x_2, x_3) | (x_1, x_2, x_3) \in B_i)$  does not depend on  $p$

Another partition

$x_1, x_2, x_3 \stackrel{iid}{\sim} \text{Bernoulli}(p)$

$T = (x_1, x_2, x_3)$

| $(x_1, x_2, x_3)$ | $T(x_1, x_2, x_3)$ | $P(x_1, x_2, x_3   T)$ |
|-------------------|--------------------|------------------------|
| $(0, 0, 0)$       | $(0, 0, 0)$        | 1                      |
| $(1, 0, 0)$       | $(1, 0, 0)$        | 1                      |
| $(0, 1, 0)$       | $(0, 1, 0)$        | 1                      |
| $\vdots$          | $\vdots$           | $\vdots$               |
| etc.              | etc.               | etc.                   |

T partitions  
 $(x_1, x_2, x_3)$

sample space into 8 groups (one per

Question: which statistic more efficiently summarizes the data?  
(i.e., results in fewer partitions?)

## Minimal sufficient statistics

Def: A statistic  $T(X_1, \dots, X_n)$  is a minimal sufficient statistic if for any other sufficient statistic  $T^*(X_1, \dots, X_n)$ ,  $T(X_1, \dots, X_n)$  is a function of  $T^*(X_1, \dots, X_n)$

Ex:  $X_1, X_2, X_3 \stackrel{iid}{\sim} \text{Bernoulli}(p)$

$$T = \sum_i X_i$$

$$T^* = (X_1, X_2, X_3)$$

$T$  is a function of  $T^*$ , but  $T^*$  is not a function of  $T$